

# Three generation seesaw model with a massless neutrino

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# Contents

- Introduction to seesaw model
- Motivation to the model with a massless neutrino
- Condition realizing a massless neutrino in the light neutrino mass spectrum
- The structure of MNSP matrix
- Comparison of the seesaw model with two right-handed neutrinos
- Numerical study
- Summary

# Introduction to the seesaw model

Seesaw model is a very attractive model which explains tiny neutrino mass

We suppose that Majorana masses are much heavier than Dirac masses.

# a general mass term of the seesaw model

$$\begin{aligned}
 L_m &= -\frac{1}{2} \begin{pmatrix} \overline{\nu_{eL}} & \overline{\nu_{\mu L}} & \overline{\nu_{\tau L}} & \overline{(N_1^c)_L} \overline{(N_2^c)_L} & \overline{(N_3^c)_L} \end{pmatrix} \begin{pmatrix} m_L & m_D \\ m_D^T & m_R \end{pmatrix} \begin{pmatrix} (\nu_e^c)_R \\ (\nu_\mu^c)_R \\ (\nu_\tau^c)_R \\ N_{1R} \\ N_{2R} \\ N_{3R} \end{pmatrix} \\
 &= -\frac{1}{2} \begin{pmatrix} \overline{\nu_{eL}} & \overline{\nu_{\mu L}} & \overline{\nu_{\tau L}} \end{pmatrix} m_L \begin{pmatrix} (\nu_e^c)_R \\ (\nu_\mu^c)_R \\ (\nu_\tau^c)_R \end{pmatrix} - \frac{1}{2} \begin{pmatrix} \overline{(N_1^c)_L} \overline{(N_2^c)_L} & \overline{(N_3^c)_L} \end{pmatrix} m_R \begin{pmatrix} N_{1R} \\ N_{2R} \\ N_{3R} \end{pmatrix} \\
 &\quad - \frac{1}{2} \begin{pmatrix} \overline{\nu_{eL}} & \overline{\nu_{\mu L}} & \overline{\nu_{\tau L}} \end{pmatrix} m_D \begin{pmatrix} N_{1R} \\ N_{2R} \\ N_{3R} \end{pmatrix} - \frac{1}{2} \begin{pmatrix} \overline{(N_1^c)_L} \overline{(N_2^c)_L} & \overline{(N_3^c)_L} \end{pmatrix} m_D^T \begin{pmatrix} (\nu_e^c)_R \\ (\nu_\mu^c)_R \\ (\nu_\tau^c)_R \end{pmatrix} \\
 &= -\frac{1}{2} \begin{pmatrix} \overline{\nu_{eL}} & \overline{\nu_{\mu L}} & \overline{\nu_{\tau L}} \end{pmatrix} m_L \begin{pmatrix} (\nu_e^c)_R \\ (\nu_\mu^c)_R \\ (\nu_\tau^c)_R \end{pmatrix} - \frac{1}{2} \begin{pmatrix} \overline{(N_1^c)_L} \overline{(N_2^c)_L} & \overline{(N_3^c)_L} \end{pmatrix} m_R \begin{pmatrix} N_{1R} \\ N_{2R} \\ N_{3R} \end{pmatrix} \\
 &\quad - \begin{pmatrix} \overline{\nu_{eL}} & \overline{\nu_{\mu L}} & \overline{\nu_{\tau L}} \end{pmatrix} m_D \begin{pmatrix} N_{1R} \\ N_{2R} \\ N_{3R} \end{pmatrix}
 \end{aligned}$$

the mass matrix

$$M_\nu = \begin{pmatrix} m_L & m_D \\ m_D^T & m_R \end{pmatrix}$$

For the simplicity, we set  $m_L=0$  and  $m_R$  is already diagonalized.

$$M_\nu = \begin{pmatrix} 0 & m_D \\ m_D^T & M \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & 0 & m_{De1} & m_{De2} & m_{De3} \\ 0 & 0 & 0 & m_{D\mu1} & m_{D\mu2} & m_{D\mu3} \\ 0 & 0 & 0 & m_{D\tau1} & m_{D\tau2} & m_{D\tau3} \\ m_{De1} & m_{D\mu1} & m_{D\tau1} & M_1 & 0 & 0 \\ m_{De2} & m_{D\mu2} & m_{D\tau2} & 0 & M_2 & 0 \\ m_{De3} & m_{D\mu3} & m_{D\tau3} & 0 & 0 & M_3 \end{pmatrix}$$

- Motivation to the model with a massless neutrino

$$M_\nu = \begin{pmatrix} 0 & 0 & 0 & m_{De1} & m_{De2} & m_{De3} \\ 0 & 0 & 0 & m_{D\mu1} & m_{D\mu2} & m_{D\mu3} \\ 0 & 0 & 0 & m_{D\tau1} & m_{D\tau2} & m_{D\tau3} \\ m_{De1} & m_{D\mu1} & m_{D\tau1} & M_1 & 0 & 0 \\ m_{De2} & m_{D\mu2} & m_{D\tau2} & 0 & M_2 & 0 \\ m_{De3} & m_{D\mu3} & m_{D\tau3} & 0 & 0 & M_3 \end{pmatrix}$$

In order that all of the eigenvalues have non-zero values, in other words, all neutrinos are massive, it is required that  $\det m_D \neq 0$ .

$$m_D = \begin{pmatrix} m_{De1} & m_{De2} & m_{De3} \\ m_{D\mu1} & m_{D\mu2} & m_{D\mu3} \\ m_{D\tau1} & m_{D\tau2} & m_{D\tau3} \end{pmatrix}$$

If  $\det m_D = 0$

we have at least one massless neutrino

proof

$$\psi_0 = \begin{pmatrix} u \\ v \end{pmatrix} \neq 0_6$$

Assuming a non-zero eigenvector that corresponds to the zero eigenvalue.

$$\begin{aligned} \mathbf{M}_\nu \mathbf{M}_\nu^\dagger \psi_0 &= 0_6 \\ h_D u + m_D M v &= 0_3 \\ \mathbf{M} \mathbf{m}_D^\dagger u + (H_D^* + M^2) v &= 0_3 \\ m_D m_D^\dagger u + m_D M v &= 0_3 \\ \mathbf{M} \mathbf{m}_D^\dagger u + (m_D^T m_D^* + M^2) v &= 0_3 \\ m_D^\dagger u + M v &= 0 \\ m_D^\dagger u &= -M v \\ \mathbf{M} \mathbf{m}_D^\dagger u + (m_D^T m_D^* + M^2) v &= -M^2 v + (m_D^T m_D^* + M^2) v \\ &= m_D^T m_D^* v \\ m_D^T m_D^* v &= 0 \\ v &= 0 \\ u &= 0 \end{aligned} \quad \left\{ \begin{array}{l} h_D = m_D m_D^\dagger \\ H_D = m_D^\dagger m_D \end{array} \right.$$

a hypothesis with self-inconsistency

- If the rank of the matrix  $m_D$  is 2,  
we have just one massless neutrino.
- If the rank of the matrix  $m_D$  is 1,  
we have two massless neutrinos.
- If the rank of the matrix  $m_D$  is 0, in effect,  $m_D$  is a  
zero matrix, we have three massless neutrinos.



Using the following unitary matrix, we can make  $M_\nu$  approximately a diagonal matrix.

$$U = \begin{pmatrix} K & m_D M^{-1} \\ -M^{-1} m_D^\dagger K & 1 \end{pmatrix}$$

$$U^\dagger M_\nu U^* = M_{\text{diag}} = \begin{pmatrix} -K^\dagger m_D \frac{1}{M} m_D^T K & 0 \\ 0 & M \end{pmatrix}$$

We define the effective mass

$$m_{\text{eff}} = -m_D \frac{1}{M} m_D^T$$

One can describe  $3 \times 3$  matrix whose rank is 2 by two independent column vectors and their linear combination.

$$\begin{aligned}
 m_D &= (m_{D1} \ m_{D2} \ m_{D3}) \\
 &= (m_{D1} \ m_{D2} \ am_{D1} + bm_{D2}) \\
 &= (m_{D1} \ m_{D2}) \begin{pmatrix} 1 & 0 & a \\ 0 & 1 & b \end{pmatrix} \\
 &= (\mathbf{u}_1 \ \mathbf{u}_2 \ \mathbf{u}_3) \begin{pmatrix} m_{D1} & 0 & 0 \\ 0 & m_{D2} & 0 \\ 0 & 0 & m_{D3} \end{pmatrix}
 \end{aligned}$$

$$= (\mathbf{u}_1 \ \mathbf{u}_2) \begin{pmatrix} 1 & 0 & a_{13} \\ 0 & 1 & a_{23} \end{pmatrix} \begin{pmatrix} m_{D1} & 0 & 0 \\ 0 & m_{D2} & 0 \\ 0 & 0 & m_{D3} \end{pmatrix}$$

$$\left\{ \begin{array}{l} |m_{D1}| = m_{D1} \\ |m_{D2}| = m_{D2} \\ |am_{D1} + bm_{D2}| = m_{D3} \\ |\mathbf{u}_1| = |\mathbf{u}_2| = |a_{13}\mathbf{u}_1 + a_{23}\mathbf{u}_2| = 1 \end{array} \right.$$

In general, we can triangulate any regular matrix with the suitable unitary matrix.

$$\Delta = V_3^\dagger m_D = \begin{pmatrix} \Delta_{D11} & 0 & 0 \\ \Delta_{D21} & \Delta_{D22} & 0 \\ \Delta_{D31} & \Delta_{D32} & \Delta_{D33} \end{pmatrix}$$

Applying this method to  $m_D$

$$\begin{aligned} V^\dagger \begin{pmatrix} \mathbf{u}_1 & \mathbf{u}_2 \end{pmatrix} &= \begin{pmatrix} \mathbf{e}_2 \times \mathbf{e}_1 \\ \mathbf{e}_2^\dagger \\ \mathbf{e}_1^\dagger \end{pmatrix} \begin{pmatrix} \mathbf{u}_1 & \mathbf{u}_2 \end{pmatrix} \\ &= \begin{pmatrix} 0 & 0 \\ 0 & \sqrt{1 - |(\mathbf{u}_2^\dagger \mathbf{u}_1)|^2} \\ 1 & \mathbf{u}_1^\dagger \mathbf{u}_2 \end{pmatrix} \end{aligned} \quad \left\{ \begin{array}{l} \mathbf{e}_2 = \mathbf{u}_2 \\ \mathbf{e}_1 = \frac{\mathbf{u}_1 - (\mathbf{u}_2^\dagger \mathbf{u}_1) \mathbf{u}_2}{\sqrt{1 - |(\mathbf{u}_2^\dagger \mathbf{u}_1)|^2}} \end{array} \right.$$

It produces the simpler form.

by  $V$  to  $2 \times 2$  components transformed matrix

$$V^\dagger m_{\text{eff}} V^* = \begin{pmatrix} 0 & 0 & 0 \\ 0 & Z_{22} & Z_{23} \\ 0 & Z_{23} & Z_{33} \end{pmatrix}$$

$$\left\{ \begin{array}{l} -Z_{22} = X_1(1 + R_{13} a_{13}^2) \cos^2 \beta \\ -Z_{23} = X_1(1 + R_{13} a_{13}^2) \sin \beta \cos \beta e^{i\gamma} + a_{13} a_{23} \sqrt{R_{13} R_{23} X_1 X_2} \cos \beta \\ -Z_{33} = X_1(1 + R_{13} a_{13}^2) \sin^2 \beta e^{2i\gamma} + 2a_{13} a_{23} \sqrt{R_{13} R_{23} X_1 X_2} \sin \beta e^{i\gamma} + X_2(1 + R_{23} a_{23}^2) \end{array} \right.$$

$$\left\{ \begin{array}{l} \sin \beta = \sqrt{1 - |(\mathbf{u}_1^\dagger \mathbf{u}_2)|^2} \\ \cos \beta e^{i\gamma} = (\mathbf{u}_1^\dagger \mathbf{u}_2) \end{array} \right.$$

$$\left\{ \begin{array}{ll} X_1 = \frac{m_{D1}^2}{M_1} & R_{13} = \frac{M_1}{M_3} \\ X_2 = \frac{m_{D2}^2}{M_2} & R_{23} = \frac{M_2}{M_3} \end{array} \right.$$

- The structure of MNSP-matrix

- $V_{MNSP} =$

$$V^\dagger \times \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & \sin\theta e^{-i\phi} \\ 0 & -\sin\theta e^{i\phi} & \cos\theta \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^{i\alpha} & 0 \\ 0 & 0 & e^{-i\alpha} \end{pmatrix}}$$

the matrix which diagonalize the  $2 \times 2$  component.

# Comparison between the seesaw model with two right- handed neutrinos and the model with three right-handed neutrinos

- (3,2) model

three left-handed neutrinos with **two right-handed neutrinos**

- (3,3)model + rank of  $m_D = 2$

A Common feature of two models **A massless neutrino**

- What about the other features ?

**CP violation and neutrino-less double beta decay, etc.**

# Dirac mass structure

$$(u_1 \quad u_2 \quad u_3) = (u_1 \quad u_2) \begin{pmatrix} 1 & 0 & a_{13} \\ 0 & 1 & a_{23} \end{pmatrix}$$

● Normalization;  $\overrightarrow{m_{Di}} = \overrightarrow{u_i} m_{Di}$

$$|u_i| = 1 (i = 1, 2, 3)$$

● Rank( $m_D$ ) = 2 ; Linearly dependent

$$u_3 = a_{13} u_1 + a_{23} u_2$$

• Convention; Im( $u_1$ )=0

# Low energy effective mass for three neutrinos

- $-m_{eff} =$

$$(u_1 \quad u_2) \begin{pmatrix} 1 & 0 & a_{13} \\ 0 & 1 & a_{23} \end{pmatrix} \begin{pmatrix} \frac{m_{D1}^2}{M_1} & 0 & 0 \\ 0 & \frac{m_{D2}^2}{M_2} & 0 \\ 0 & 0 & \frac{m_{D3}^2}{M_3} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ a_{13} & a_{23} \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

- $= (u_1 \quad u_2) \begin{pmatrix} X_1 + a_{13}^2 X_3 & a_{13} a_{23} X_3 \\ a_{13} a_{23} X_3 & X_2 + a_{23}^2 X_3 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix},$   
 $X_i = \frac{m_{Di}^2}{M_i}$

- Two limits  $M_3 \rightarrow \infty$ , or  $a_{13}, a_{23} \rightarrow 0$  lead to the same effective mass as (3,2) Model.



# Two cases which lead to $m_{\text{eff}}$ similar to (3,2) model.

$$1. (a_{13}, a_{23}) = (e^{i\frac{\varphi_{13}}{2}}, 0); (u_1 \quad u_2 \quad u_3) = (u_1 \quad u_2) \begin{pmatrix} 1 & 0 & e^{i\frac{\varphi_{13}}{2}} \\ 0 & 1 & 0 \end{pmatrix}$$

$$\bullet m_{\text{eff}} = -(u_1 \quad u_2) \begin{pmatrix} X_1 + X_3 e^{i\varphi_{13}} & 0 \\ 0 & X_2 \end{pmatrix} \begin{pmatrix} u_1^T \\ u_2^T \end{pmatrix}$$

$$2. (a_{13}, a_{23}) = (0, e^{i\frac{\varphi_{23}}{2}}); (u_1 \quad u_2 \quad u_3) = (u_1 \quad u_2) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & e^{i\frac{\varphi_{23}}{2}} \end{pmatrix}$$

$$\bullet m_{\text{eff}} = -(u_1 \quad u_2) \begin{pmatrix} X_1 & 0 \\ 0 & X_2 + X_3 e^{i\varphi_{23}} \end{pmatrix} \begin{pmatrix} u_1^T \\ u_2^T \end{pmatrix}$$

# Mixing matrix and mass with orthogonality assumption ( $\mathbf{u}_2^+ \mathbf{u}_1 = 0$ )

- MNSP

matrix ;  $V_{MNSP} = (\mathbf{u}_2^* \times \mathbf{u}_1^*, \mathbf{u}_2, \mathbf{u}_1)P$

- $V_{MNS}^+ m_{eff} V_{MNSP}^* = P^+ \begin{pmatrix} 0 & 0 & 0 \\ 0 & -X_2 & 0 \\ 0 & 0 & -(X_1 + X_3 e^{i\varphi_{13}}) \end{pmatrix} P^* =$

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & m_2 & 0 \\ 0 & 0 & m_3 \end{pmatrix}, P = \text{diag.} (1, e^{i\frac{\pi}{2}}, e^{i\frac{\alpha+\pi}{2}}), \tan \alpha = \frac{X_3 \sin \varphi_{13}}{X_1 + X_3 \cos \varphi_{13}}$$

$$m_3 = \sqrt{X_1^2 + 2X_1 X_3 \cos \varphi_{13} + X_3^2}, m_2 = X_2$$

# Mixing Matrix

- $V_{MNSP} = \begin{pmatrix} V_{e1} & V_{e2} & V_{e3} \\ V_{\mu 1} & V_{\mu 2} & V_{\mu 3} \\ V_{\tau 1} & V_{\tau 2} & V_{\tau 3} \end{pmatrix}$
- $(u_2^* \times u_1^* - u_2 u_1) = \begin{pmatrix} u_{\mu 2}^* u_{\tau 1}^* - u_{\tau 2}^* u_{\mu 1}^* & u_{e2} & u_{e1} \\ u_{\tau 2}^* u_{e1}^* - u_{e2}^* u_{\tau 1}^* & u_{\mu 2} & u_{\mu 1} \\ u_{e2}^* u_{\mu 1}^* - u_{\mu 2}^* u_{e1}^* & u_{\tau 2} & u_{\tau 1} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^{i\frac{\pi}{2}} & 0 \\ 0 & 0 & e^{i\frac{\alpha+\pi}{2}} \end{pmatrix}$

( Our convention; **Im.  $\mathbf{u}_1=0$** )

# Tuning the Standard notation form of MNSP to our convention

$$U = \begin{bmatrix} c_{12}c_{13} & s_{12}c_{13} & s_{13}e^{-i\delta} \\ -s_{12}c_{23} - c_{12}s_{23}s_{13}e^{i\delta} & c_{12}c_{23} - s_{12}s_{23}s_{13}e^{i\delta} & s_{23}c_{13} \\ s_{12}s_{23} - c_{12}c_{23}s_{13}e^{i\delta} & -c_{12}s_{23} - s_{12}c_{23}s_{13}e^{i\delta} & c_{23}c_{13} \end{bmatrix} \\ \times \text{diag}(1, e^{i\frac{\alpha_{21}}{2}}, e^{i\frac{\alpha_{31}}{2}}) .$$

$$V_{MNSP} = \begin{pmatrix} C_{12}C_{13}e^{i\delta} & S_{12}C_{13}e^{i\delta} & S_{13} \\ -S_{12}C_{23} - C_{12}S_{23}S_{13}e^{i\delta} & C_{12}C_{23} - S_{12}S_{23}S_{13}e^{i\delta} & S_{23}C_{13} \\ S_{12}S_{23} - C_{12}C_{23}S_{13}e^{i\delta} & -C_{12}S_{23} - S_{12}C_{23}S_{13}e^{i\delta} & C_{23}C_{13} \end{pmatrix} \\ \times \text{diag.}(1, e^{i\alpha_{21}/2}, e^{i\alpha_{31}/2})$$

# Determination of seesaw parameters

$$m_3 = \sqrt{X_1^2 + 2X_1 X_3 \cos \varphi_{13} + X_3^2} ; m_2 = X_2$$

$$(\mathbf{u}_1 \quad \mathbf{u}_2 \quad \mathbf{u}_3) = (\mathbf{u}_1 \quad \mathbf{u}_2) \begin{pmatrix} 1 & 0 & e^{i\frac{\varphi_{13}}{2}} \\ 0 & 1 & 0 \end{pmatrix}$$

$$(\mathbf{u}_1 \quad \mathbf{u}_2) = \begin{pmatrix} S_{13} & S_{12} C_{13} e^{i\delta} \\ S_{23} C_{13} & C_{12} C_{23} - S_{12} S_{23} S_{13} e^{i\delta} \\ C_{23} C_{13} & -C_{12} S_{23} - S_{12} C_{23} S_{13} e^{i\delta} \end{pmatrix}$$

$$\tan \frac{X_3 \sin \varphi_{13}}{X_1 + X_3 \cos \varphi_{13}} = \tan \alpha, \alpha_{21} = \pi, \alpha_{31} = \pi + \alpha$$

# Determination of seesaw parameters from the observables

- Mixings ,  $S_{12}=0.55$ , ,  $S_{23}=0.71$ , ,  $S_{13}=0.15$
- $C_{12}=0.83$ , ,  $C_{23}=0.70$ , ,  $C_{13}=0.99$
- Mass,
- Normal hierarchy ;
- $m_1 = 0, m_2 = \sqrt{\Delta m_{21}^2} = 0.00867756(\text{eV}),$
- $m_3 = \sqrt{\Delta m_{21}^2 + \Delta m_{32}^2} = 0.0501528(\text{eV})$

# CP violation of neutrino oscillation and neutrino-less double beta decay

- CP violation of neutrino oscillation

$$P(\nu_\mu \rightarrow \nu_e) - P(\bar{\nu}_\mu \rightarrow \bar{\nu}_e) \quad J = \text{Im}(V_{e1}^{\text{MNS}} V_{\mu 1}^{\text{MNS}*} V_{e2}^{\text{MNS}*} V_{\mu 2}^{\text{MNS}})$$

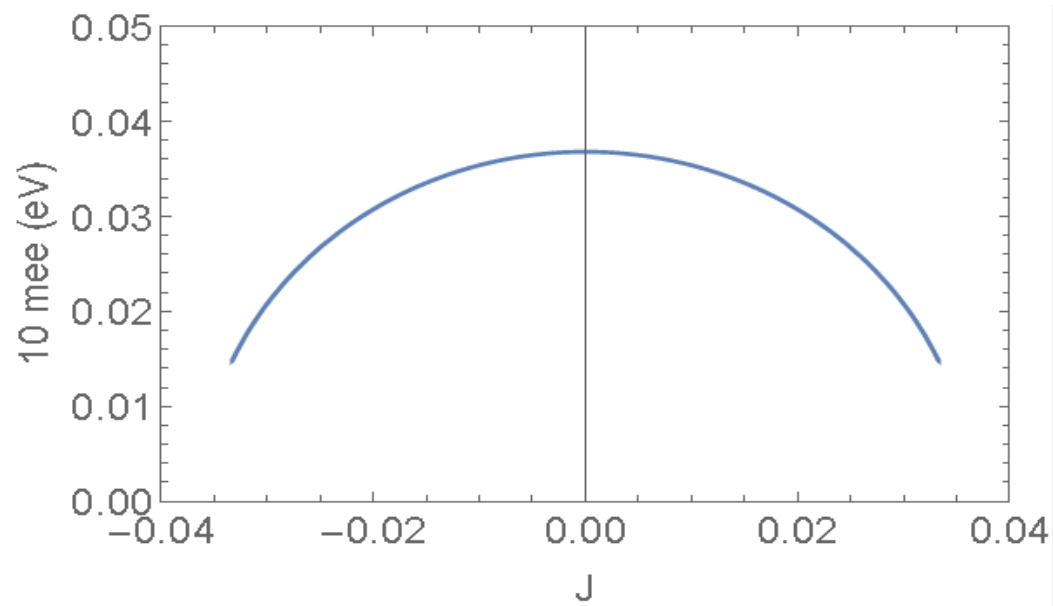
$$= 4J \left( \sin \frac{\Delta m_{12}^2 L}{2E} + \sin \frac{\Delta m_{23}^2 L}{2E} + \sin \frac{\Delta m_{31}^2 L}{2E} \right)$$

$$J = C_{12} S_{12} C_{23} S_{23} C_{13}^2 S_{13} \sin \delta$$

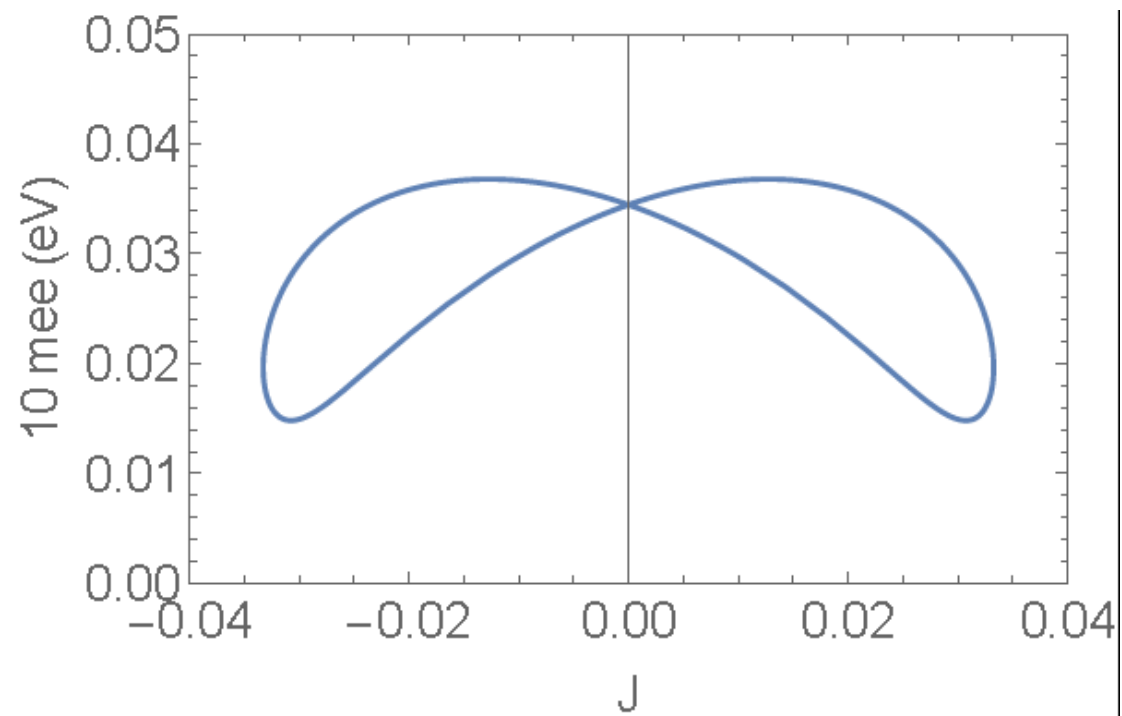
- Neutrino-less double beta decay

$$\begin{aligned} |m_{eff}| &= |V_{MNSe2}^2 m_2 + V_{MNSe3}^2 m_3| \\ &= |S_{12}^2 C_{13}^2 m_2 + S_{13}^2 m_3 e^{i(\alpha - 2\delta)}| \end{aligned}$$

$$\alpha = 0$$



$$\alpha = \frac{\pi}{4}$$





# Summary

- Three generation seesaw model with a massless neutrino is studied.
- Condition realizing a massless neutrino in the light neutrino mass spectrum  
 $\text{Rank}(m_D)=2$
- A common structure with (3,2) model giving rise to a massless neutrino is pointed out.
- A specific case for  $m_D$  is numerically studied.  
A correlation bet.  $J$  (CPV of oscillation) and  $m_{ee}$  of neutrino-less double beta decay